L Number	Hits	Search Text	DB	Time stamp
13	0	robot same (graphic\$4 display\$3 screen) same (3-d	USPAT;	2004/09/01
		3d three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:06
		US-5486995-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion mov\$4 animat\$4)	DERWENT;	
		and (adjust\$4 modif\$) near2 (dimension\$2 siz\$3)	IBM_TDB	
		near2 model\$4 and (@ad<19991012 @rlad<19991012)		-
14	0	700/259 and (graphic\$4 display\$3 screen) same (3-d	USPAT;	2004/09/01
		3d three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:09
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	-
		(model\$4 simulat\$4) same (motion mov\$4 animat\$4)	DERWENT;	
		and ((stor\$3 memory database) and adjust\$4) near4	IBM_TDB	
		(model\$4 simulat\$4) and (@ad<19991012		
		@rlad<19991012)		
15	4	l	USPAT;	2004/09/01
	·	3d three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:10
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion mov\$4 animat\$4)	DERWENT;	
		and ((stor\$3 memory database) and adjust\$4) near4	IBM_TDB	
		(model\$4 simulat\$4) and (@ad<19991012	_	
		@rlad<19991012)		
16	0	robot same (graphic\$4 display\$3 screen) same (3-d	USPAT;	2004/09/01
	J	3d three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:19
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion mov\$4 animat\$4)	DERWENT;	
		and ((stor\$3 memory database) and (adjust\$4	IBM_TDB	
		modif\$) and select\$4) near2 model\$4 and		
		(@ad<19991012 @rlad<19991012)		
18	9	robot same (graphic\$4 display\$3 screen) same (3-d	USPAT;	2004/09/01
10	,	3d three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:16
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion mov\$4 animat\$4)	DERWENT;	
		and ((stor\$3 memory database) and (adjust\$4	IBM_TDB	
		modif\$) select\$4) near2 model\$4 and	20.1100	
		(@ad<19991012 @rlad<19991012)		
17	15	robot same (graphic\$4 display\$3 screen) same (3-d	USPAT;	2004/09/01
17		3d three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:16
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	10.10
		(model\$4 simulat\$4) same (motion mov\$4 animat\$4)	DERWENT;	
		and ((stor\$3 memory database) (adjust\$4 modif\$)	IBM_TDB	
İ		and select\$4) near2 model\$4 and (@ad<19991012	10//_100	
		@rlad<19991012)		
21	1	robot and (graphic\$4 display\$3 screen) same (3-d 3d	USPAT;	2004/09/01
c1	1	three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:41
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	10.41
		(model\$4 simulat\$4) same (motion mov\$4 animat\$4)	DERWENT;	
			IBM_TDB	
		and ((stor\$3 memory database) and (adjust\$4	TOW_I DB	
ŀ		modif\$) and select\$4) near2 model\$4 and		
		(@ad<19991012 @rlad<19991012)	<u> </u>	1

22	0	robot and (graphic\$4 display\$3 screen) same (3-d 3d	USPAT;	2004/09/01
		three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:42
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion animat\$4) and	DERWENT;	
		((stor\$3 memory database) and (adjust\$4 modif\$)	IBM_TDB	
		and select\$4) near2 model\$4 and (@ad<19991012	1511_100	
		· ·		
22		@rlad<19991012)	USPAT;	2004/09/01
23	0	robot and (graphic\$4 display\$3 screen) same (3-d 3d	US-PGPUB;	10:42
		three-dimension\$2 three-d 3-dimension\$2 (three	EPO; JPO;	10.42
		U5-5880956-A.DID.) near (dimension\$2 d)) same	DERWENT;	
		(model\$4 simulat\$4) same (motion animat\$4) and	ì	
		((stor\$3 memory database) and (adjust\$4 modif\$)	IBM_TDB	
		and select\$4) near2 (dimension\$ siz\$3) near2		
		model\$4 and (@ad<19991012 @rlad<19991012)	<u>_</u>	
.24	0	robot and (graphic\$4 display\$3 screen) same (3-d 3d	USPAT;	2004/09/01
		three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:54
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion animat\$4) and	DERWENT;	
		((stor\$3 memory database) and (adjust\$4 modif\$)	IBW_TDB	
		and select\$4) near2 (dimension\$ siz\$3) and	,	
*		(@ad<19991012 @rlad<19991012)	•	
25	36	robot and (graphic\$4 display\$3 screen) same (3-d 3d	USPAT;	2004/09/01
-		three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	10:55
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion animat\$4) and	DERWENT;	
		((stor\$3 memory database) (adjust\$4 modif\$) and	IBM_TDB	
		select\$4) near2 (dimension\$ siz\$3) and		
		(@ad<19991012 @rlad<19991012)		
26	0	345/419 and robot and (graphic\$4 display\$3 screen)	USPAT;	2004/09/01
		same (3-d 3d three-dimension\$2 three-d	US-PGPUB;	10:59
		3-dimension\$2 (three US-5880956-A.DID.) near	EPO; JPO;	
		(dimension\$2 d)) same (model\$4 simulat\$4) same	DERWENT;	
		(motion animat\$4) and ((stor\$3 memory database)	IBM_TDB	
		and select\$4) near2 model\$4 and (adjust\$4 modif\$)		
		near2 (dimension\$ siz\$3) and (@ad<19991012		
		@rlad<19991012)		
27	0	345/\$ and robot and (graphic\$4 display\$3 screen)	USPAT;	2004/09/01
		same (3-d 3d three-dimension\$2 three-d	US-PGPUB;	11:00
		3-dimension\$2 (three US-5880956-A.DID.) near	EPO; JPO;	
		(dimension\$2 d)) same (model\$4 simulat\$4) same	DERWENT;	
		(motion animat\$4) and ((stor\$3 memory database)	IBW_TDB	
		and select\$4) near2 model\$4 and (adjust\$4 modif\$)		
		near2 (dimension\$ siz\$3) and (@ad<19991012		
		@rlad<19991012)		
28	0	robot and (graphic\$4 display\$3 screen) same (3-d 3d	USPAT;	2004/09/01 11:01
		three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion animat\$4) and	DERWENT;	
		((stor\$3 memory database) and select\$4) near2	IBM_TDB	
		model\$4 and (adjust\$4 modif\$) near2 (dimension\$		
1		siz\$3) and (@ad<19991012 @rlad<19991012)		

29	0	robot and (graphic\$4 display\$3 screen) same (3-d 3d	USPAT;	2004/09/01 11:01
		three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	
		U5-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
İ		(model\$4 simulat\$4) same (motion animat\$4) and	DERWENT;	
		(stor\$3 memory database) with model\$4 and	IBM_TDB	
		select\$4 near2 model\$4 and (adjust\$4 modif\$)		ē
		near2 (dimension\$ siz\$3) and (@ad<19991012		
		@rlad<19991012)		
30	13	robot and (graphic\$4 display\$3 screen) same (3-d 3d	USPAT;	2004/09/01
30		three-dimension\$2 three-d 3-dimension\$2 (three	US-PGPUB;	11:02
		US-5880956-A.DID.) near (dimension\$2 d)) same	EPO; JPO;	
		(model\$4 simulat\$4) same (motion animat\$4) and	DERWENT;	
		((stor\$3 memory database) and select\$4) with	IBM_TDB	
		model\$4 and (adjust\$4 modif\$) near2 (dimension\$		
		siz\$3) and (@ad<19991012 @rlad<19991012)		
31	14	robot same (motion animat\$4) and (graphic\$4	USPAT;	2004/09/01
31		display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	11:03
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
٠		((stor\$3 memory database) and select\$4) with	IBM_TDB	
		model\$4 and (adjust\$4 modif\$) near2 (dimension\$	_	
		siz\$3) and (@ad<19991012 @rlad<19991012)		
32	2	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01 11:12
32	_	display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		((stor\$3 memory database) and select\$4) with	IBM_TDB	
		model\$4 and (adjust\$4 modif\$) near2 (dimension\$	·	
		siz\$3) and (@ad<19991012 @rlad<19991012)		
33	2	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01 11:13
	_	display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		(stor\$3 memory database) near3 model\$4 and	IBM_TDB	
		(adjust\$4 modif\$) near2 (dimension\$ siz\$3) and		
		(@ad<19991012 @rlad<19991012)		
34	2	1.	USPAT;	2004/09/01
	_	display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	11:08
,		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		(adjust\$4 modif\$) near2 (dimension\$ siz\$3) and	IBM_TDB	
		(@ad<19991012 @rlad<19991012)	1	
35	13	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01
		display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	11:09
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		(stor\$3 memory database) near3 model\$4 and	IBM_TDB	
		(@ad<19991012 @rlad<19991012)	1	

38	0	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01 11:12
		display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		((stor\$3 memory database) and select\$4 and	IBM_TDB	
		(adjust\$4 modif\$) near2 (dimension\$ siz\$3)) with		
		model\$4 and (@ad<19991012 @rlad<19991012)		
39	0	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01 11:12
"	J	display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		((stor\$3 memory database) and select\$4 and	IBM_TDB	
		(adjust\$4 modif\$) near2 (dimension\$ siz\$3)) same		
		model\$4 and (@ad<19991012 @rlad<19991012)		
40	2	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01 11:14
•0	۷	display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		(stor\$3 memory database library) near3 model\$4 and	IBM_TDB	
			IPW_100	
		(adjust\$4 modif\$) near2 (dimension\$ siz\$3) and		
	•	(@ad<19991012 @rlad<19991012)	USPAT;	2004/09/01 11:14
11	2	robot same (motion animat\$4) same (graphic\$4		2004/09/01 11:14
		display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		(stor\$3 memory database library) near3 model\$4 and	IBW_TDB	
		(adjust\$4 modif\$) near3 (dimension\$ siz\$3) and		
		(@ad<19991012 @rlad<19991012)		0004400404
42	2	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01
		display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	14:20
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		(adjust\$4 modif\$) near3 (dimension\$ siz\$3) and	IBM_TDB	
		(@ad<19991012 @rlad<19991012)		
47	3	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01
		display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	14:24
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		constraint same (stor\$3 memory database library)	IBW_TDB	
		and (@ad<19991012 @rlad<19991012)		
50	2	robot same (motion animat\$4) same (graphic\$4	USPAT;	2004/09/01
		display\$3 screen) same (3-d 3d three-dimension\$2	US-PGPUB;	14:24
		three-d 3-dimension\$2 (three US-5880956-A.DID.)	EPO; JPO;	
		near (dimension\$2 d)) same (model\$4 simulat\$4) and	DERWENT;	
		constraint with (stor\$3 memory database library)	IBM_TDB	
		and (@ad<19991012 @rlad<19991012)		